

# Solids Summer 2002 Final Exam Equations

KML 8/2/02

$$\text{Axial: } \sigma = \frac{P}{A} \quad \epsilon = \frac{\delta L}{L}$$

$$\text{Hooke's Law for axial stress} \quad \sigma = E \cdot \epsilon \quad \text{Poisson's Ratio} \quad \nu = -\frac{\epsilon_{\text{lat}}}{\epsilon_{\text{ax}}}$$

$$\text{Average shear stress} \quad \tau = \frac{V}{A}$$

$$\text{Average bearing stress} \quad \sigma_b = \frac{P}{A_b} \quad \text{Hooke's Law in shear} \quad \tau = G \gamma$$

$$\text{Safety factor} = \frac{\text{failure stress}}{\text{allowable stress}} \quad n_{\text{ult}} = \frac{\sigma_{\text{ult}}}{\sigma_{\text{all}}} \quad n_y = \frac{\sigma_y}{\sigma_{\text{all}}} \quad n_{sy} = \frac{\tau_y}{\tau_{\text{all}}} \quad \text{MS} = n - 1$$

$$\text{Axial deflection} \quad \delta = \frac{PL}{AE} \quad \text{Axial stiffness} \quad k = \frac{AE}{L}$$

$$\text{Thermal deflection} \quad \delta L_{\text{th}} = L \cdot \alpha \cdot \Delta T \quad \text{Thermal stress} \quad \sigma_{\text{th}} = E \alpha \Delta T$$

$$\text{Thermal statically indeterminant} \quad \sum \frac{R \cdot L_i}{A_i \cdot E_i} = 0$$

$$\text{Normal stress concentration} \quad \sigma_{\text{max}} = K \cdot \sigma_{\text{nom}}$$

$$\text{Max torsional stress} \quad \tau_{\text{max}} = \frac{T \cdot r}{I_p} \quad \text{Shear stress at any radius, } r; \quad \tau = \frac{T}{I_p} \cdot r$$

$$\text{Angle of twist} \quad \phi = \frac{T \cdot L}{G \cdot I_p} \quad \text{Torsional stiffness} \quad k_T = \frac{G \cdot I_p}{L}, \quad T = k_T \cdot \phi$$

$$\text{Torsional shear strain} \quad \gamma_{\text{max}} = \frac{r \phi}{L} \quad \text{Solid shaft} \quad I_p = \frac{\pi \cdot d^4}{32} = \frac{\pi \cdot r^4}{2} \quad \tau_{\text{max}} = \frac{16 \cdot T}{\pi \cdot d^3}$$

$$\text{Annulus} \quad I_p = \frac{\pi}{32} (d_o^4 - d_i^4)$$

$$\text{Shear stress concentration} \quad \tau_{\text{max}} = K \cdot \tau_{\text{nom}}$$

$$\text{Power and torque} \quad P = T \omega \quad \omega = 2\pi f \quad \omega = \frac{\pi RPM}{30} \quad P_{\text{hp}} = \frac{(T \text{ ft} \cdot \text{lbs}) \cdot \text{RPM}}{5252}$$

$$\text{Bending stress} \quad \sigma_x = -\frac{M_z \cdot y}{I_z}$$

$$\text{Solid rectangular beams} \quad I = \frac{bh^3}{12}, \quad \sigma_{\text{max}} = \frac{6M}{bh^2}$$

$$\text{Solid circular beams} \quad I = \frac{\pi d^4}{64}, \quad \sigma_{\text{max}} = \frac{32M}{\pi d^3}$$

Parallel axis theorem       $I_z = \bar{I}_z + A \cdot d_{zz}^2$       Centroid:       $\bar{y} = \frac{\sum(\bar{y}_i \cdot A_i)}{\sum A_i}$

Widen material2:  $\sigma_{x1} = -\frac{M y}{I_T}$      $\sigma_{x2} = -\frac{M y}{I_T} \cdot n$       Narrow material1:  $\sigma_{x1} = -\frac{M y}{n \cdot I_T}$      $\sigma_{x2} = -\frac{M y}{I_T}$      $n = \frac{E_2}{E_1}$

Stress from moment and axial force load       $\sigma_x = \frac{P_x}{A} - \frac{M_z \cdot y}{I_z}$       Location of neutral axis       $y_0 = \frac{P \cdot I}{A \cdot M}$

Transverse shear stress:       $\tau = \frac{V Q}{I b}$        $Q = A \cdot \bar{y}_s$

Solid rectangular beam:       $\tau_{max} = \frac{3 V}{2 A}$        $\tau = \frac{V Q}{I b} = \frac{V}{2 I} \cdot \left( \frac{h^2}{4} - y^2 \right) = \frac{6 V}{b h^3} \cdot \left( \frac{h^2}{4} - y^2 \right)$

Solid circular beam:       $\tau_{max} = \frac{4 V}{3 A}$

Stress transformations:       $\tau_{x1y1} = -\frac{\sigma_x - \sigma_y}{2} \cdot \sin(2\theta) + \tau_{xy} \cdot \cos(2\theta)$        $\sigma_{y1} = \sigma_{x1}(\theta + 90^\circ)$

$$\sigma_{x1} = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cdot \cos(2\theta) + \tau_{xy} \cdot \sin(2\theta) \quad \sigma_{y1} = \frac{\sigma_x + \sigma_y}{2} - \frac{\sigma_x - \sigma_y}{2} \cdot \cos(2\theta) - \tau_{xy} \cdot \sin(2\theta)$$

$$\sigma_{avg} = \frac{\sigma_x + \sigma_y}{2} \quad R = \sqrt{\left( \frac{\sigma_x - \sigma_y}{2} \right)^2 + \tau_{xy}^2} \quad \left| \sin 2\theta_p \right| = \frac{|\tau_{xy}|}{R} \quad \sigma_{1,2} = \sigma_{avg} \pm R$$

Plane Stress       $\sigma_x = \frac{E}{1-v^2} \cdot (\epsilon_x + v \epsilon_y)$        $\sigma_y = \frac{E}{1-v^2} \cdot (\epsilon_y + v \epsilon_x)$        $\tau_{xy} = G \gamma_{xy}$        $G = \frac{E}{2 \cdot (1+v)}$   
 $\epsilon_x = \frac{1}{E} (\sigma_x - v \sigma_y)$        $\epsilon_y = \frac{1}{E} (\sigma_y - v \sigma_x)$        $\epsilon_z = \frac{-v}{E} (\sigma_x + \sigma_y)$

Spherical pressure vessels:       $\sigma = \frac{p r}{2 t}$        $\tau_{max} = \frac{p r}{4 t}$

Cylindrical pressure vessels:       $\sigma_1 = \frac{p r}{t}$        $\sigma_2 = \frac{p r}{2 t}$        $\tau_{max} = \frac{p r}{2 t}$

Deflection charts provided on additional pages.

Buckling:       $P_{cr} = \frac{\pi^2 E I}{L_e^2}$

Pinned-pinned:  $L_e = L$       Fixed-free:  $L_e = 2L$       Fixed-fixed:  $L_e = 0.5 L$       Fixed-pinned:  $L_e = 0.699 L$